

# BRONE

DRONE FACILITY FOR TESTING SENSORS AND  
DATA COLLECTION FOR USE IN DRONE-BASED  
INSPECTION OF INFRASTRUCTURE  
AND BUILDINGS.



## KNOWLEDGE PARTNERS



DANISH  
TECHNOLOGICAL



Technical University  
of Denmark

INNO  
DRONE  
PART OF THE INNO-DRONE PROJECT

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AND BUILDINGS.

## BRONE: Experiences and Lessons



KNOWLEDGE PARTNERS



DANISH  
TECHNOLOGICAL



Technical University  
of Denmark

Wilson Ricardo Leal da Silva, PhD  
Building and Construction Division

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DRONE  
PART OF THE INNO-DRONE PROJECT

# BRONE in a nutshell



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The **BRONE Living Lab** is a collaborative outdoor space where companies can test their existing solutions and demonstrate new concepts.

The core project objectives are to:

- a) establish a living lab for test / development of drone-based inspection;
- b) experiment by testing drone-based inspection technologies;
- c) share knowledge;
- d) foster new research and product development ventures.

From **BRAINSTORMING** → to **LIVING LAB ACTIVITIES**



# BRONE Phase 1 – Brainstorming

Participants: **Dansk Drone Kompagni, Drone Harmony, Drone Systems, Easy Inspect, Scopito, Spotland, and STO Danmark**

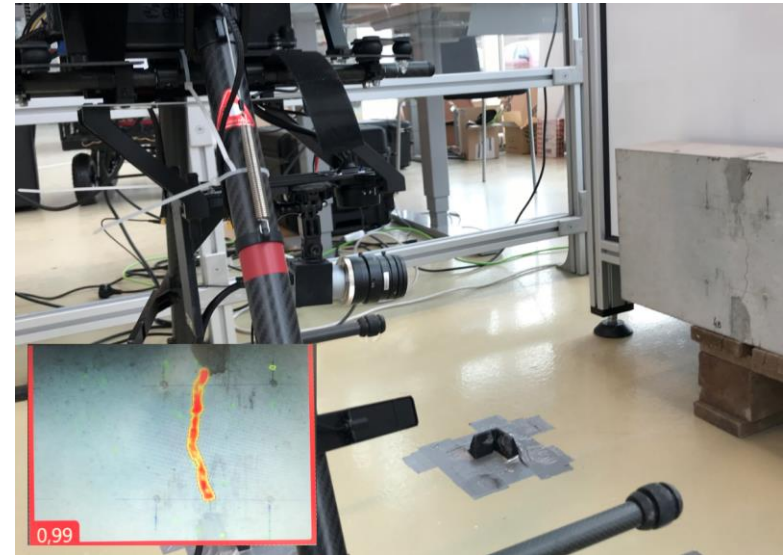
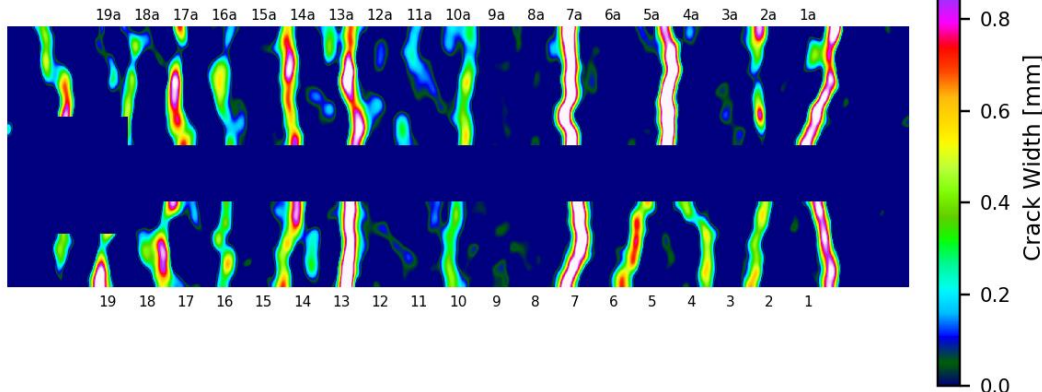
# 2. Technologies



## WHICH TECHNOLOGY EXPERIMENTS SHALL WE FOCUS ON?

- Artificial-Intelligence-based inspection → detecting anomalies in concrete/masonry;
- LIDAR and other sensors → monitoring relative deformation on existing structures;

### Drone-based Digital Image Correlation

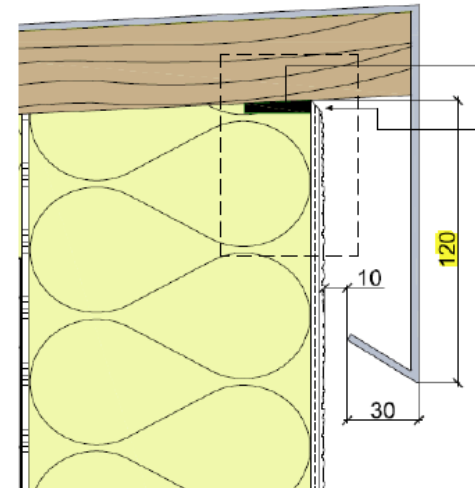
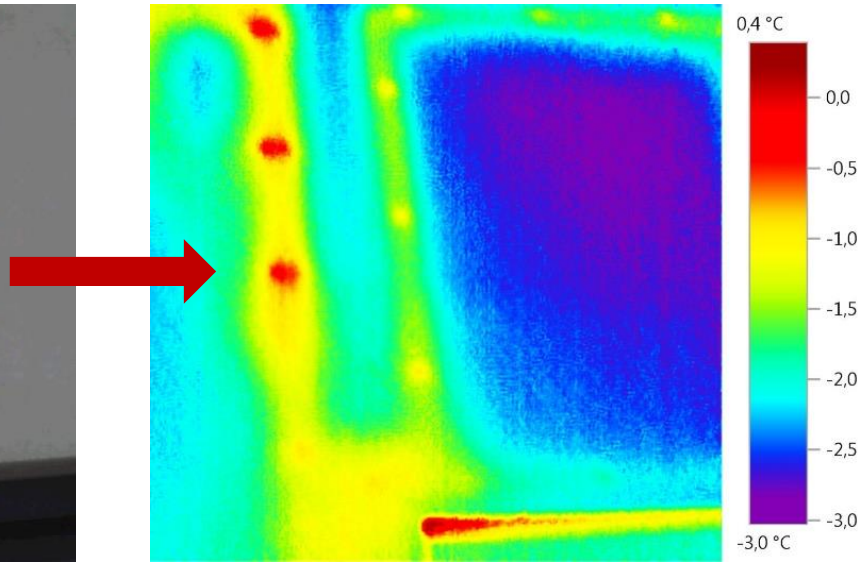


# 2. Technologies



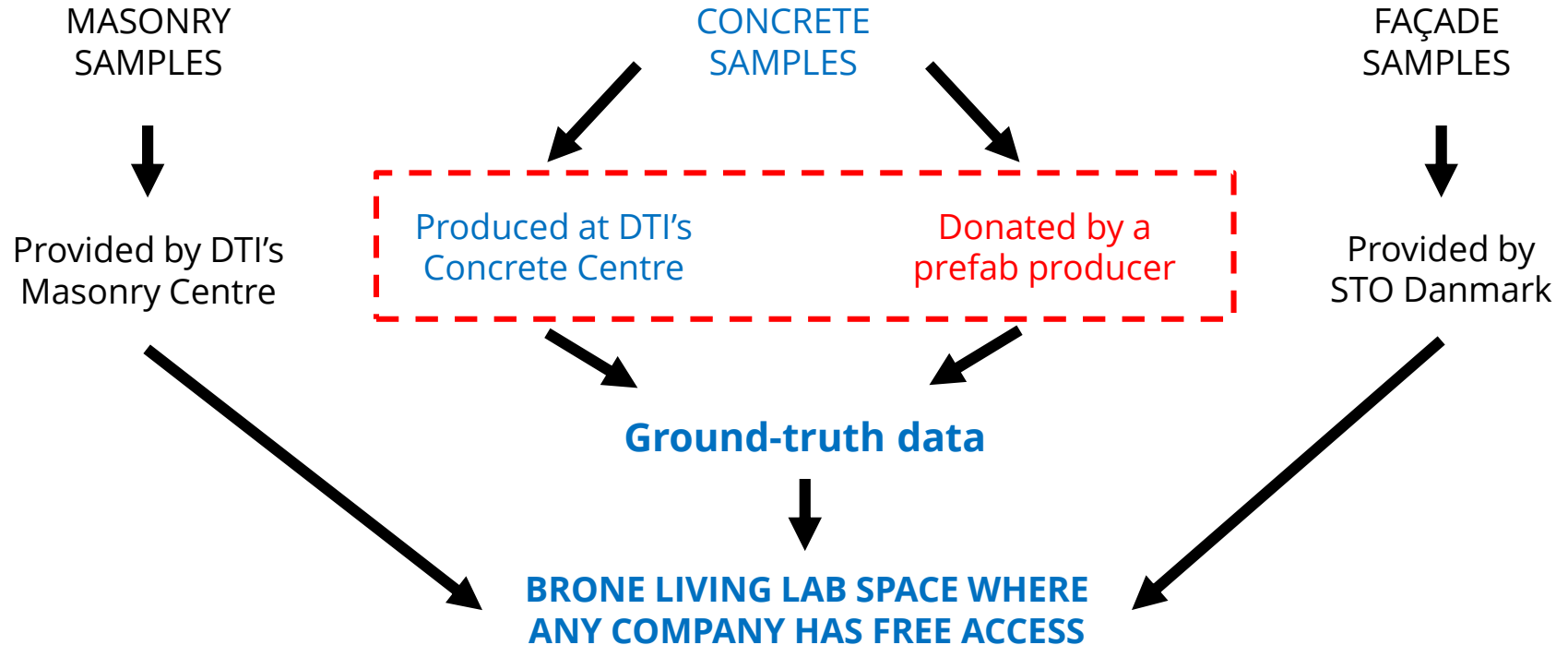
## WHICH TECHNOLOGY EXPERIMENTS SHALL WE FOCUS ON?

- Thermal cameras → heat-maps of concrete elements (e.g. on-site QC);
- Façade elements monitoring → alignment/surface area in existing buildings (QC);



# 2. Technologies

## DAMAGE ASSESSMENT IN BUILDING AND INFRASTRUCTURES



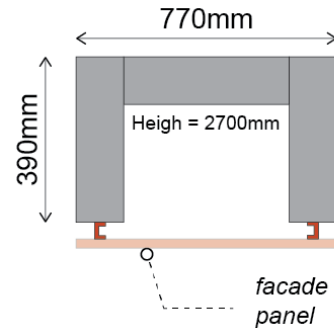
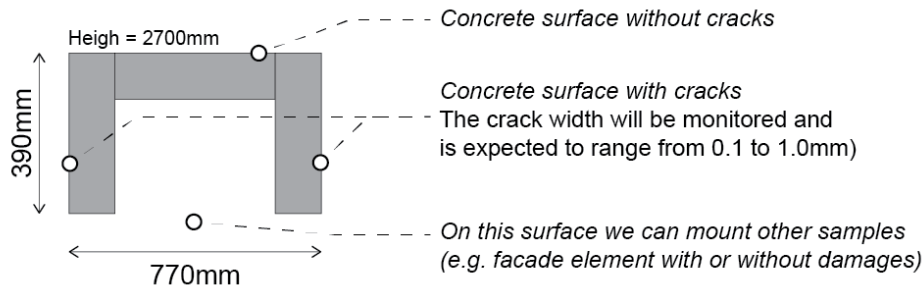
# 3. BRONE Mock-up



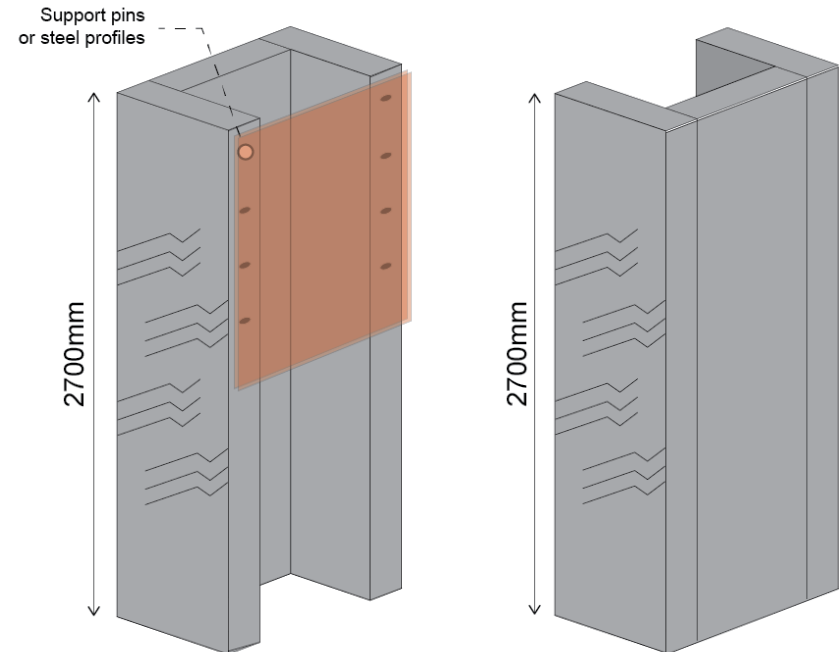
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## BRONE MOCK-UP

Top view: Large-scale concrete sample



Perspective





# 3. BRONE Mock-up



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## BRONE MOCK-UP - Individual samples before 4-Point Bending Testing



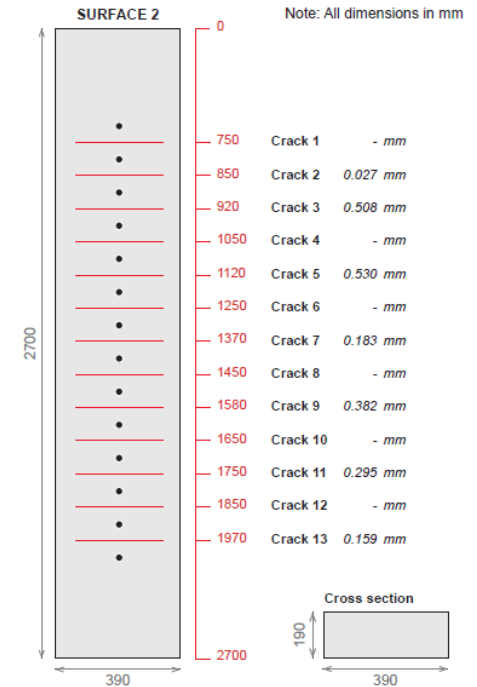
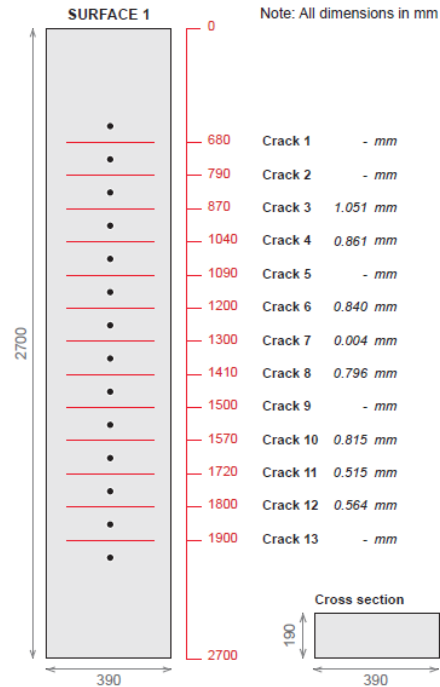
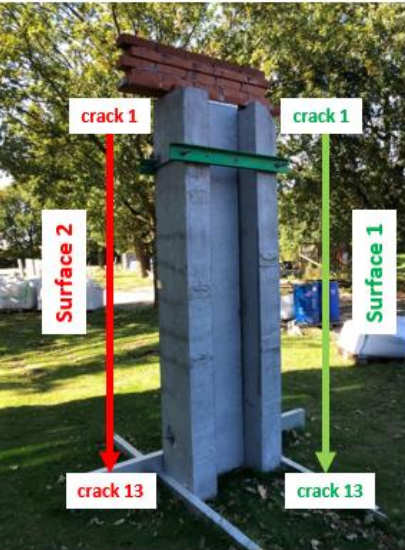
# 3. BRONE Mock-up (Testing)



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# 3. BRONE Mock-up (Results)





# BRONE Phase 2 – Living Lab

# 4. BRONE Living Lab



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## TECHNOLOGIES

- Artificial-Intelligence (Crack detection)
- AI-assisted inspection (Point cloud)
- Laser scanning (Digital annotation)
- Numerical modelling (moisture ingress)

easy@inspect

SPOTLAND



Omsorgsfuldt byggeri.

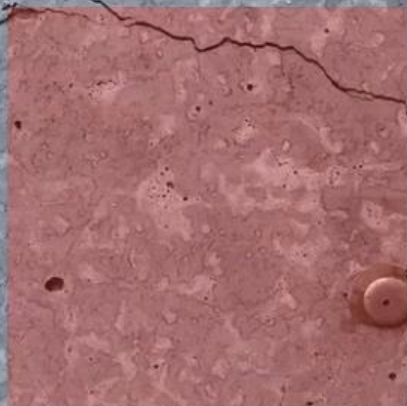


# BRONE SAMPLE

AI-based crack detection analysis (threshold = 0.15):

Crack: 0.000

No Crack:



# 4.2 Concrete Inspection (Inspection Cloud)

Dashboard

Inspection details

Tools

- Image
- Point Cloud (beta)

Point Cloud

Navigation mode

Point sizing

ADAPTIVE

Point size

1

Color type

RGB

Unit system

Metric

Camera size scaling

Filtered images: 30 (filter)

Issue-7

Issue-1

Issue-8

Issue-2

Issue-9

Issue-3

Issue-4

Issue-10

Issue-5

Issue-11

Issue-6

Issue-12

DJI\_0005.JPG

Measurements

Issues

- Issue-1
- Issue-10
- Issue-11
- Issue-12
- Issue-13
- Issue-2
- Issue-3

Image annotations

Image details

DJI\_0016.JPG

7 annotations

DJI\_0015.JPG

No annotations

DJI\_0006.JPG

No annotations

DJI\_0047.JPG

No annotations

DJI\_0005.JPG

7 annotations

DJI\_0048.JPG

No annotations



# 4.2 Laser Scanning (Point Cloud)

☰ Search ✕

🔧 **S2C5 = 0.530mm**  
Floor: 0

🔗  
SHARE

Crack width = 0.530mm



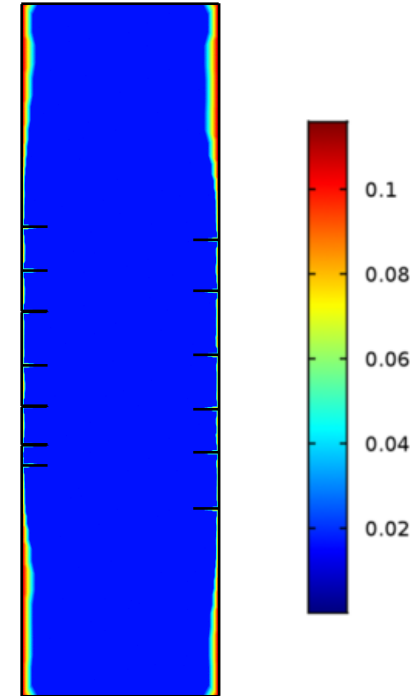
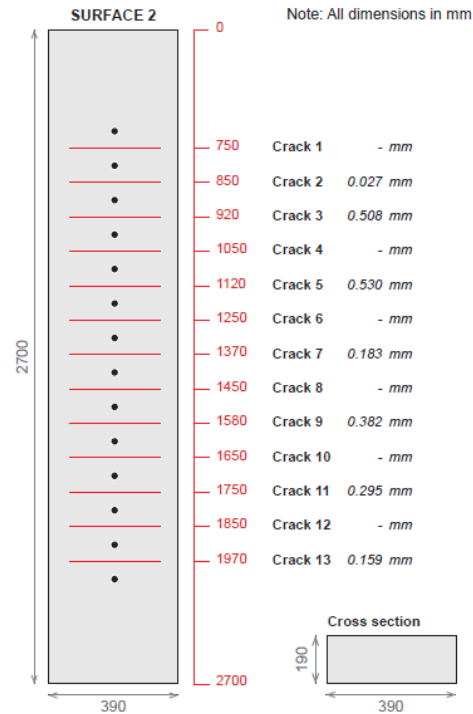
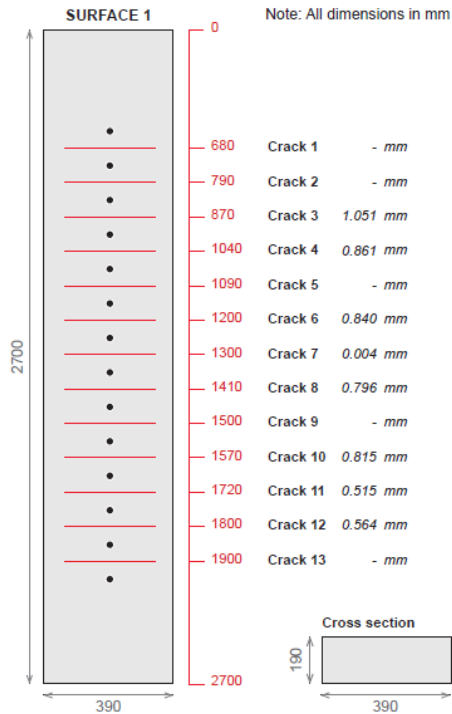
🔧 **S2C5 = 0.530mm**

🔧 **S2C5 = 0.530mm**



# 4.4 Numerical Modelling

*Moisture ingress model based on crack width ( $>0.1\text{ mm}$ )*



Thank you for your attention and participation

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